PHASE FAILURE DETECTOR AND A DEVICE COMPRISING THE SAME

The present invention relates to a phase failure detector, according to the preamble of Claim 1, and a device including a phase failure detector.

Phase failure detectors of this kind are used in multi-phase voltage-supply networks, to detect a loss of, or reduction in voltage in one or several phases.

A phase failure detector is a particularly important component in many assemblies utilizing a mains power supply. In many assemblies, the loss of, or a significant reduction in even one phase will cause problems. Problems can be caused, for example, by the power supply or system being fed becoming loaded unevenly when one phase is missing entirely, or is significantly reduced. The asymmetry created can also cause make control of the system difficult, or cause other disturbances. Problems can also arise during the stage when the phase voltage is restored to normal.

Examples of systems requiring phase failure detectors include power supplies for three-phase motors, transformers, rectifiers, and network inverters. Particularly in rectifier solutions, in which a semi-controlled thyristor bridge is used, it is important that even short network breaks can be detected, to ensure that control of the bridge does not continue in diode mode once mains voltage has been restored. In such solutions, this is because intermediate circuit voltage can crash during an outage, resulting in fuses blowing when the power supply voltage is restored, leading to a break in the operation of a process.

Phase failure detectors can thus be used in many different industrial applications, in ships, and in a national power supply network.

Patent US 3 001 100 discloses one solution for monitoring the operation of a multi-phase network. The solution requires an auxiliary voltage source (8; 26) at the potential of the network voltage and cannot be used to determine which of the phases are defective. The solution is also slow to operate, making it unsuitable for use with modern frequency converters, for example. The slowness of the solution is due to half-wave direction (4;

22) and the time constants. The circuit disclosed also does not differentiate between a normal loss of voltage in all phases and a lack of one or two phases. The circuit will also not operate in a floating network lacking a neutral conductor.

Patent US 4 027 204 discloses a second solution for monitoring the operation of a multi-phase network. This solution can indeed operate without a separate auxiliary voltage source at the potential of the network, but the necessary auxiliary power is taken through resistances (31, 32, 33, and 37), leading to a significant power loss in normal operation, particularly if it is desired to cover a large voltage range. Due to the heavy power consumption, the solution cannot be sensibly implemented, for example, integrated in a circuit board. The rectifying diodes (12) in the circuit must also be able to withstand the voltage peaks occurring in the network voltage, thus requiring components with a very high reverse voltage capacity when using higher voltages. Another basic problem with the circuit is that it cannot be used to detect which of the phases have been lost. The circuit also does not distinguish between a normal voltage break in which all phases are lost and one in which one or two phases are lacking.

Application publication SU 1 332 448 discloses a third solution for monitoring the operation of a multi-phase network. This solution is based on electromechanical auxiliary relays (3, 4, 5, 17, and 20), the coils of which are powered through voltage divider capacitors (1). At normal network frequencies, operation requires quite large capacitance values, making the integration of the solution in a circuit board neither sensible nor even possible. The circuit also does not detect a missing phase, or a normal voltage outage in all phases. In addition, the solution operates so slowly that it is unsuitable for use, for example, in connection with modern frequency converters. The slowness is due to the electromechanical components. In addition the solution is expensive and demands a large amount of space.

Object of the invention is to create a simple and inexpensive phase failure detector, which will not only detect a fault state, but also which of the phases is defective.

The invention is based on the phase failure detector being equipped with a separate detector circuit for each phase being monitored. The detector circuits are connected

between the phase being monitored and a common connection point, so that the common connection point forms a reference level. This reference level can be floating, in which case it corresponds to a virtual star point of the power supply network. The reference level can also be connected to a real star point, a ground potential, or some other suitable potential. The detector circuit itself includes voltage-divider elements, and a trigger circuit and detector, to which the voltage being monitored is fed in a reduced form from the voltage-divider elements.

More specifically, the phase failure detector according to the invention is characterized by what is stated in the characterizing portion of Claim 1.

The device, according to the invention, utilizing a multi-phase mains power supply is, in turn characterized by what is stated in the characterizing portion of Claim 9.

Considerable advantages are gained with the aid of the invention.

With the aid of the invention, it is possible to implement a simple and inexpensive phase failure detector, which can detect not only a fault state, but also which of the phases is defective.

The invention also has numerous embodiments, by means of which significant additional advantages are gained.

In an embodiment, in which the detector circuits are connected to a common reference point with a known potential, the phase failure detector can also detect a fault state, in which all phases are defective.

The invention permits the phase failure detector to be designed with an extremely simple construction. In such a simple embodiment, only a few discrete components are required for the phase failure detector and the manufacturing costs remain very small. The phase failure detector can also be integrated on a circuit board and manufactured with a very small physical size.

The invention also permits a circuit solution that can be applied to a wide mains-voltage range. A circuit solution according to some embodiments can be applied, as such, to the entire low-voltage range, and, with the aid of voltage transformers, also to medium and high voltages.

An additional advantage is also achieved using embodiments, in which the capacitor or capacitors of the voltage divider elements are used as an energy store and the power for the trigger circuit and detector is supplied from this energy store. In such embodiments, the trigger circuit and the detector do not need an auxiliary power supply or a separate energy supply; instead the necessary energy is obtained directly from the electricity network being monitored.

The invention also permits galvanic separation from the systems separating fault information.

One interesting application of the invention is a power inverter used in a motor power feed. The phase failure detector can then be incorporated in the equipment assembly and set to monitor the alternating voltage being fed to the rectifier. If the common connecting point of the detector circuits of the phase failure detector is connected to the reference potential leading from the direct-voltage circuit of the rectifier, for example, to the medium voltage of the direct-voltage circuit (the potential level in the middle of the minus and plus potentials), the phase failure detector will be able to detect each defective phase, independently of the operation of the other phases.

In the following, the invention is examined with the aid of examples and with reference to the accompanying drawings.

Figure 1 shows one phase failure detector according to the invention, connected to a three-phase voltage supply.

Figure 2 shows a diagram of the detector circuit of the phase failure detector of Figure 1.

Figure 3 shows a voltage-vector presentation of an functioning three-phase system.

Figure 4 shows a voltage-vector presentation of a three-phase system, in which the voltage of one phase has been lost.

Figure 5 shows a circuit diagram of one phase failure detector according to the invention.

The following example describes the use of the invention in three-phase systems, which are the simplest of the systems that can be used as examples. However, the corresponding principles can also be used in other multi-phase systems and particularly in systems in which the phases are multiples of three (n x 3-phase system).

Figure 1 shows a phase failure detector 1 for a three-phase electricity supply network. The phase failure detector 1 includes a separate detector circuit 3, which has a first connection point 4 and a second connection point 5, for each phase 2 of the electricity supply network. The first connection point 4 of each detector circuit 3 is connected electrically to the connection point 12 of the phase 2 monitored by the detector circuit 3. The second connection points 5 of the detector circuits 3 are, in turn, connected to a common connection point 9 of the detector circuits, which corresponds to a star point of the electricity supply network being monitored. The connection point 9 can therefore be termed a virtual start point. In the circuit of Figure 1, the connection point 9 is floating, so that it is not connected to a real start point of the electricity supply network - which is why it is called a virtual star point. The phase failure detector of Figure 1 can, of course, also be connected to an external ground point, a star point, or corresponding reference level, with the aid of a connector 11 connected to the connection point 9.

Figure 2 shows the detector circuit 3 used in the phase failure detector of Figure 1 in greater detail. The detector circuit 3 of Figure 2 includes capacitive voltage divider elements 6, which are connected between the first connection point 4 and the second connection point 5. Thus, the voltage divider elements 6 divide the voltage (phase voltage) between the phase 2 and the virtual star point 9, as reduced voltage. The voltage divider elements 6 are typically made from capacitors, as capacitors have certain advantageous properties. For example, capacitors have low power consumption. In

addition, capacitors act as an energy store, which offers excellent possibilities for the operation of the detector circuit 3. Connected to the voltage divider elements 6 is an input point 7, to which the divided voltage is led, and through which the energy stored in the voltage divider elements 6 can be discharged. The detector circuit 3 also includes a trigger and detector circuit 8, which is connected between the input point 7 and the second connection point 5.

The trigger and detector circuit 8 is a circuit, which produces a detection pulse, when the voltage in the input point 7 reaches a trigger level. A suitable triac or thyristor circuit, for example, can be utilized in the trigger circuit. The trigger is designed to activate, for example, always when the absolute value of the voltage of the input point 7 (which thus follows the phase voltage) rises to a specific trigger level. Thus, during one cycle of alternating voltage, the trigger and detector circuit 8 produce two detection pulses, if the phase 2 being monitored functions normally. The detection pulse can be transmitted onwards from the circuit 8 to monitoring equipment (not shown) that detects a fault state, if the detection pulses are not received within a predefined time. In principle, this reaction time can be even less that the cycle of the alternating voltage, but in most applications an alarm or fault notification is only worth making after a longer period without pulses, for example, 1 - 5 seconds. In a preferred embodiment, the trigger and detector circuit 8 takes its energy from the energy store contained in the voltage divider element 6. Such an embodiment is very simple and, in addition, the use of it achieves the considerable advantage that a fault state is also detected if the circuit 3 itself becomes defective. Thus, in a fault state of the phase failure detector 1, it is not possible to draw the erroneous conclusion that there is no defect in the voltage supply.

The link between the trigger and detector circuit 8 and the monitoring equipment can be designed to be galvanically isolated. Thus, the detection pulse can be transmitted, for example, with the aid of a pulse of light or sound.

The following describes the operation of the phase failure detector 1 in a phase fault situation, with the aid of the vector presentations of Figures 3 and 4. The voltages of a three-phase system can be shown using three phase-voltage vectors. Figure 3 shows such a presentation. If the voltage supply network is symmetrical, the absolute values of the

voltage vectors, relative to the star point 9, are of the same magnitude and at an angle of 120 degrees to each other.

If, however, one of the phase inputs fails (for example, phase U), the voltage-vector presentation takes the form shown in Figure 4. The voltage vectors of the two remaining phases 2 are still mutually of the same magnitude, but there is a phase transfer of 180 degrees between them, i.e. they are in opposite directions. The apparent star point 9 has moved to the middle of the straight line between the points of the vectors.

If phase U has failed, the length of the sector corresponding to the voltage of phase U is zero and the entire sector is still located in the aforementioned apparent star point 9, because, in the phase failure detector 1, the voltage divider 6 of the phase 2 in question is connected to the common star point 9. Thus, no voltage of any kind acts over the voltage divider 6 of the defective phase. The trigger and detector circuit 8 of phase U therefore does not give a detection pulse.

Figure 5 shows one extremely simple circuit, by means of which the phase failure detector shown in Figures 1 and 2 can be implemented. In the circuit shown in Figure 5, each of the phases U, V, and W being monitored is connected against the virtual star point 9 by the voltage divider (voltage divider elements 6) formed by the resistance R1 and the capacitors C1 and C2. A voltage acts over the capacitor C2, its magnitude depending on the component values, the phase voltage, and the network frequency.

The voltage acting over the capacitor C2 is led, through the resistance R2 and the Zener diodes V1 and V2, to the gate of the triac V3 (trigger and detector circuit 8). If the voltage exceeds the Zener voltage, a gate current begins to flow to the triac, in which case it is triggered to a conducting state. The capacitor C2 now discharges through the resistance R2, the bridge V4, the LED of the opto-link V5, and the triac V3, thus creating a current pulse. The amplitude and duration of the pulse will depend on the values of the resistance R2 and the capacitor C2.

The energy of the capacitor C2 thus discharges through the LED of the opto-link, so that the light of the LED puts the receiver of the opto-link momentarily into a conducting

state. This state is indicated in a suitable manner, for example, by generating an interrupt request to a micro-controller.

In the circuit of Figure 5, the task of the resistance R1 is to limit the surge current travelling through the capacitors C1 and C2 when the device is switched on and in cases in which there are rapidly rising and falling voltage peaks or notched voltage edges in the network voltage. In three-phase supply applications, the resistance R1 has a resistance value typically in the order of a kilo-ohm and should withstand a power of at least a couple of watts.

The voltage acting over the capacitor C2 can be selected freely by altering the values of the voltage-divider components C1 and C2. In practice, the effect of the resistance R1 on the division ratio of the voltage is of no significance. The level of the capacitance of the capacitors can be selected to be such that the rms current (effective current - root mean square), at the greatest network frequency used, is about 10 - 15 mA. Thus, if the available network (main) voltage is 600 volts at a frequency of 60 hertz, or 690 volts at a frequency of 50 hertz, the total capacitance of the voltage divider can be in the order of magnitude of 100 nF.

About 15 volts is typically selected as the value of the Zener diodes V1 and V2 defining the trigger value of the triac V3, in which case the value of the resistance R2 limiting the current of the LED can be, for example 470 ohms. R2 thus protects the LED from excess current and, on the other hand, slows the discharge of the capacitor C2, thus prolonging the light pulse obtained from the LED. As the trigger current of the small triac used in this connection is in the order of a few milliamperes, the peak voltages acting over the capacitor C2 need be only slightly greater than the Zener voltage, for the triac V3 to trigger.

The voltage division is used to set the trigger voltage to correspond to the network voltage level at which it is wished for detection of the missing phase to occur. Thus, if it is wished for the phase failure detector to operate in the nominal voltage range of 400 - 690 volts, a suitable detection level for a missing phase could be, for example, 280 volts. The phase voltage level seen by the phase failure detector is 160 volts$_{rms}$, i.e. at a peak

value of about 225 volts, so that the voltage division ratio using 15-volt Zener diodes
will be about 15. This is achieved with sufficient accuracy by selecting 100 nF as the
value of the capacitor C1 and 1,5 µF (microfarads) as the value of the capacitor C2. The
capacitor C1 should withstand the entire network voltage, whereas 25 volts, for instance,
will be a sufficient voltage resistance for the capacitor C2.

At the detection level and an alternating voltage of 50 hertz, a peak current of about six
milliamperes will travel through the voltage divider, which is eminently sufficient to
trigger the triac.

The embodiment disclosed above are not intended to restrict the scope of the patent
protection, instead embodiments of the invention, differing from those disclosed above,
can also be envisaged.